Developing a Multiserver Operating System

Jakub Jermář February 3, 2010 UINX.CZ

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microkernel			

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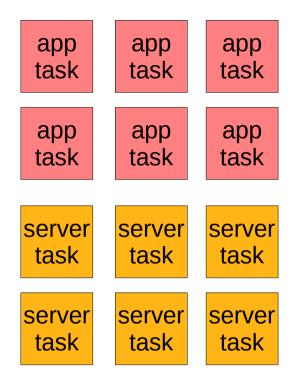
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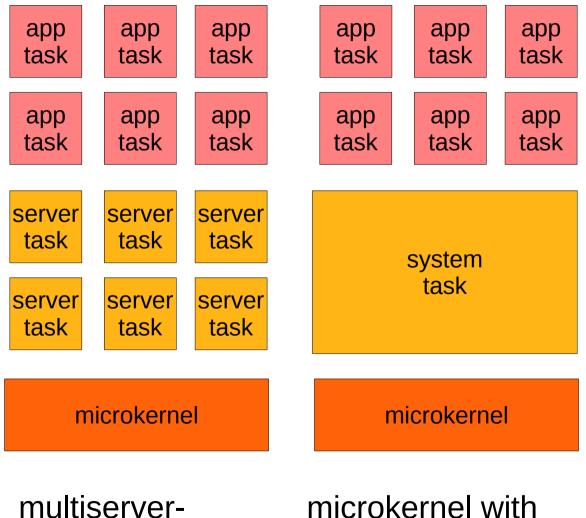
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- not every OS is microkernel-based

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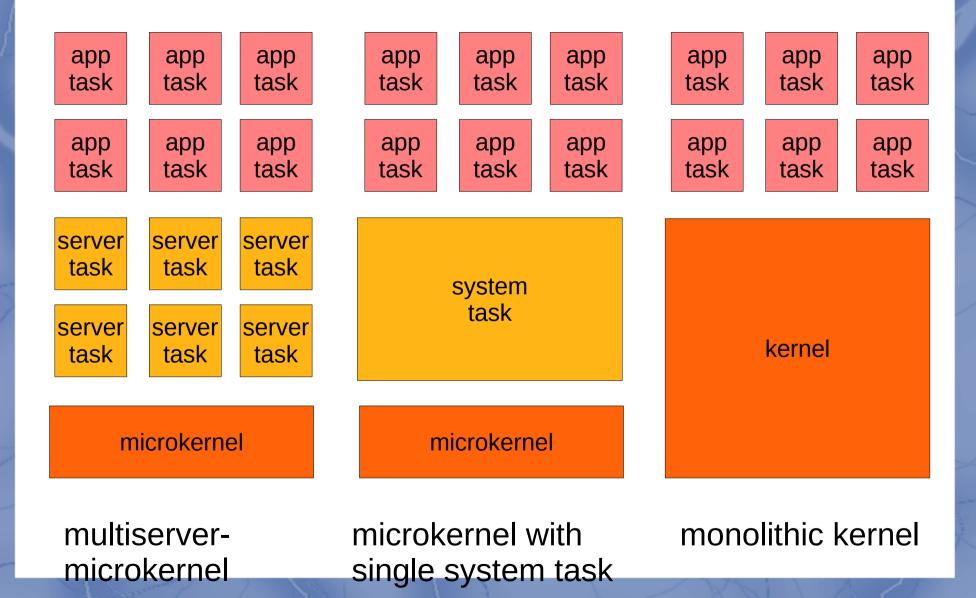
microkernel

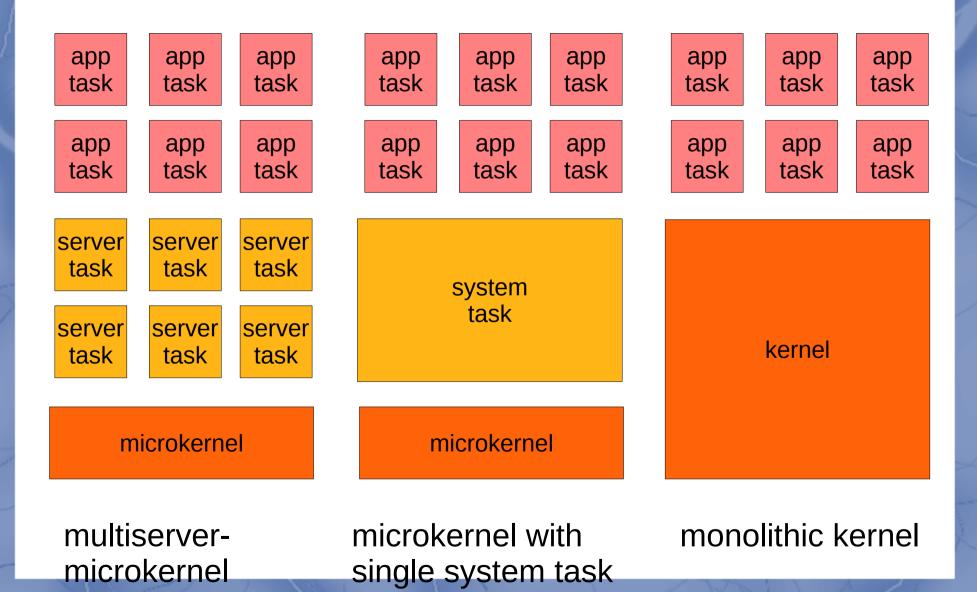
multiservermicrokernel

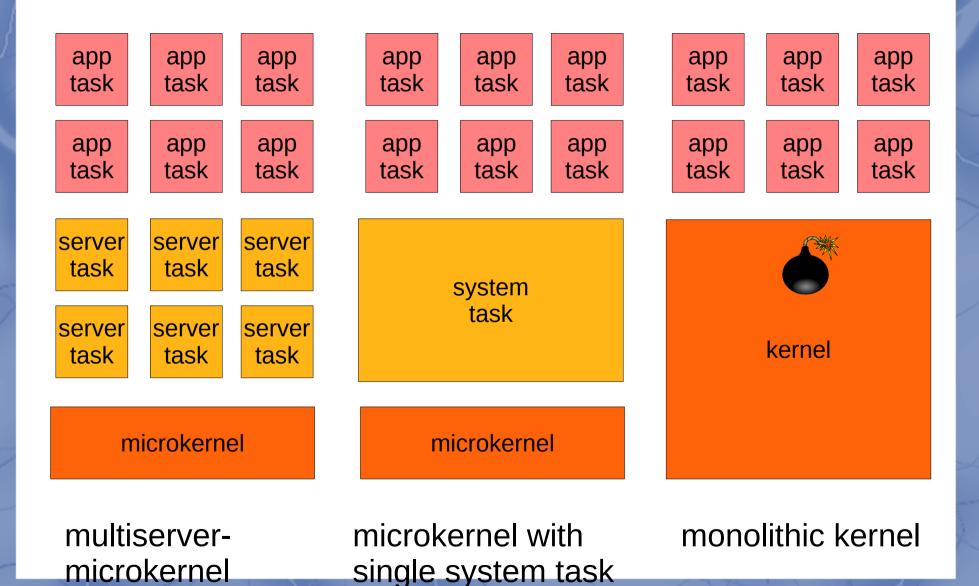


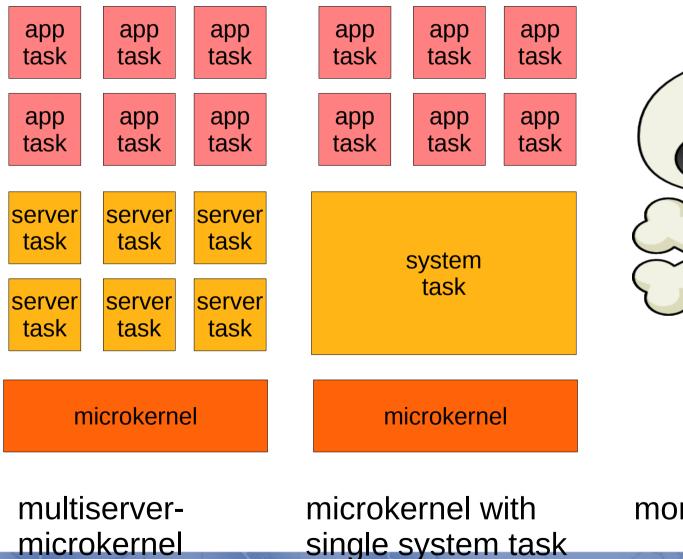
microkernel

microkernel with single system task



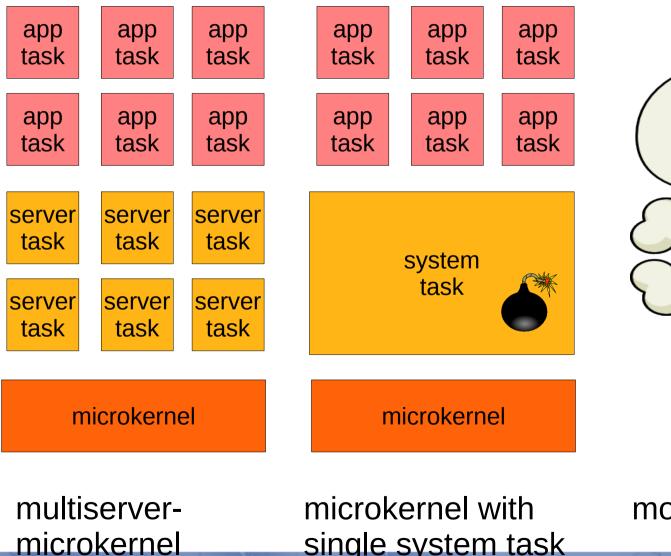






monolithic kernel

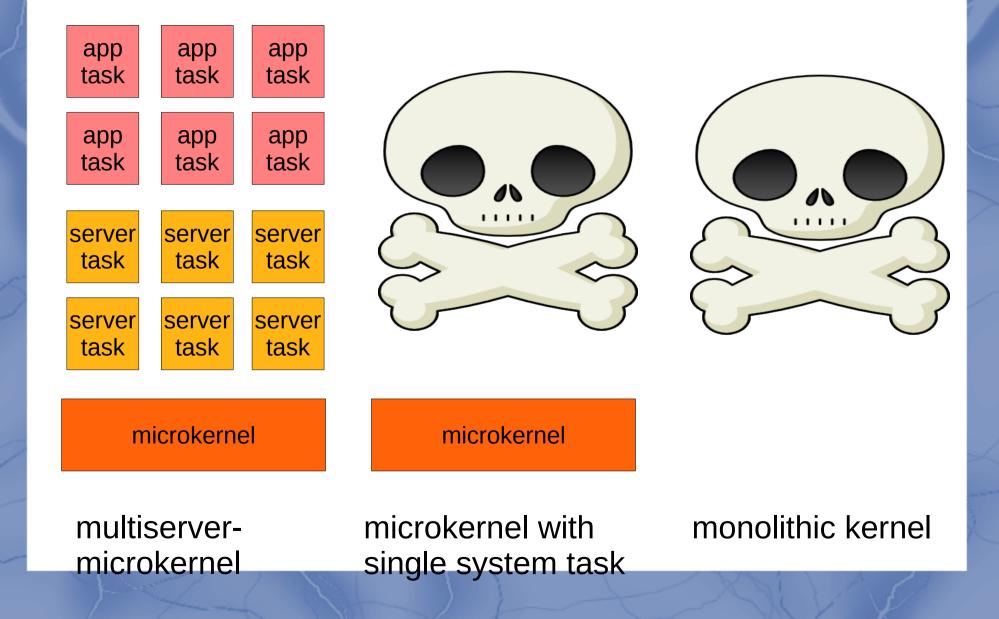
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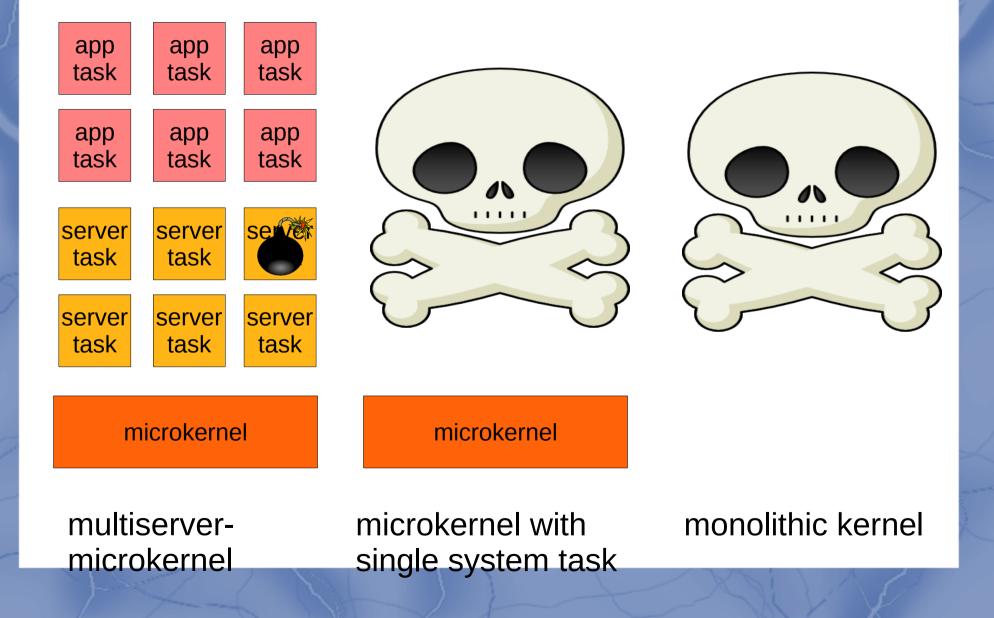


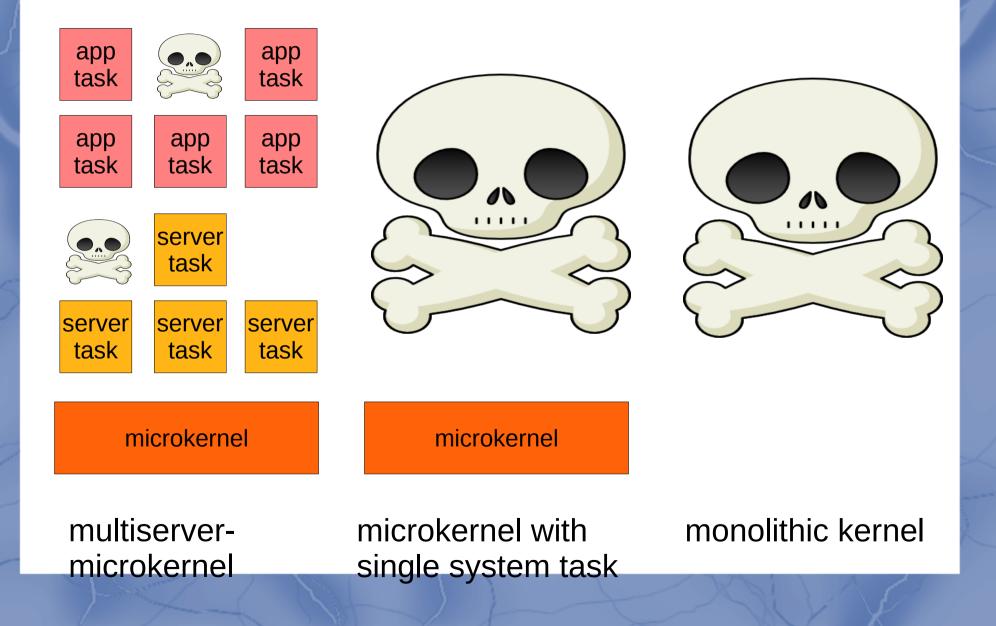


single system task

monolithic kernel







Pros and Cons Overview

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Pros

- Improved robustness and fault isolation
- Clean interface between servers
- Simpler components
- Flexibility in connecting components

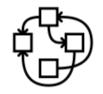
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- Clean interface between servers
- Simpler components
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Cons

- Worse performance
- No cross-layer optimizations



Hurd http://hurd.gnu.org





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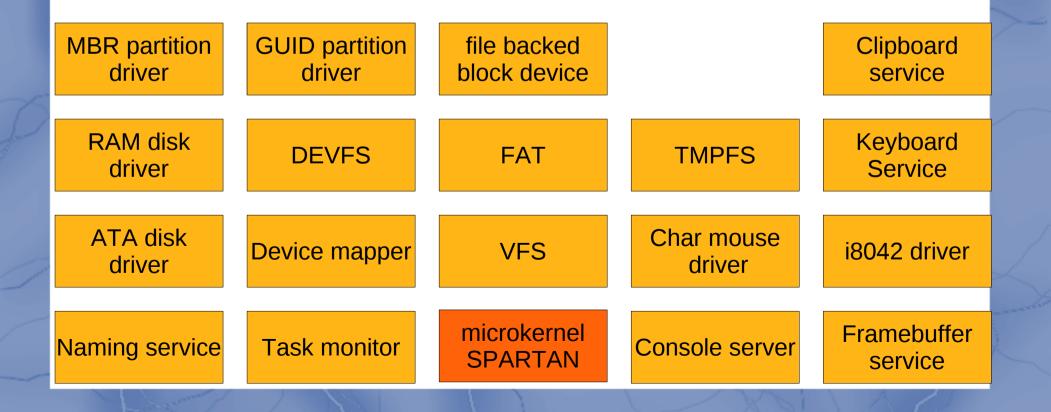






Hurd http://hurd.gnu.org MINIX 3 http://minix3.org HelenOS http://helenos.org

microkernel SPARTAN



Ethernet	nildummy		ТСР	UDP
dp8390 driver	loopback driver	ICMP	IP	ARP
MBR partition driver	GUID partition driver	file backed block device	Network packet server	Clipboard service
RAM disk driver	DEVFS	FAT	TMPFS	Keyboard Service
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- Some servers may even run in multiple instances
- All servers provide some services to other server tasks or applications; most servers require services from other servers
- Together these server tasks provide the services of the operating system

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- Message passing provided by the kernel
 IPC

Message passing

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 unusual metaphor of making phone calls and leaving a message in the answerbox

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 - Asynchronous
- Number of communicating tasks can be 1, 2 or N
 - communicating with self
 - communicating with a peer
 - peer forwards the call to third party

HelenOS IPC (II)

- Message ~ Phone call
 - simple calls
 - combo calls

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- Message ~ Phone call
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 - Six 32-bit / 64-bit words of payload
- Combo calls
 - memory sharing
 - large data block copying
 - tasks negotiate, kernel arbitrates

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 - the components understand a protocol
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 - the protocol can have many implementations
 - object oriented design

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- It also brings some problems
 - writing IPC by hand is tedious compared to mere function calls in monolithic designs
 - could be generated from some high level architecture description
 - all HelenOS IPC written by hand so far
 - it is difficult to implement non-trivial protocols using asynchronous IPC
 - callbacks and event loops
 - HelenOS has a framework for it

Asynchronous framework

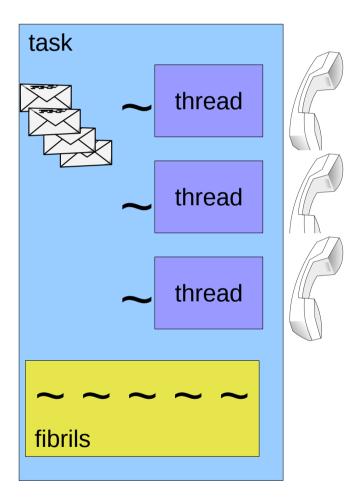
Asynchronous framework

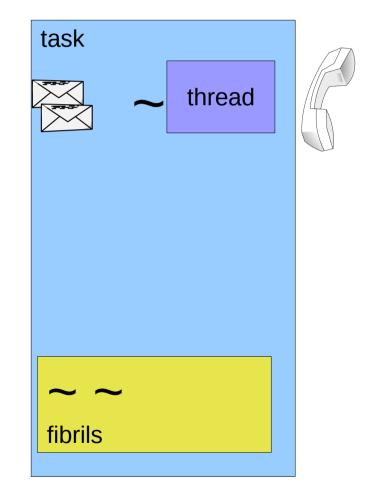
- Makes the asynchronous communication a pleasant experience
 - no event loops
 - no callbacks

Asynchronous framework

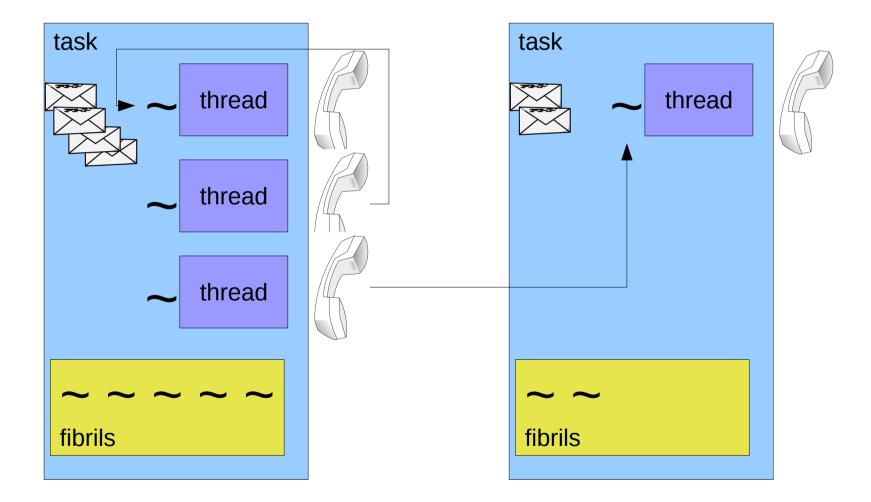
- Makes the asynchronous communication a pleasant experience
 - no event loops
 - no callbacks
- Introduces fibrils (userspace threads) to already multithreaded tasks
 - client's connection handled by a fibril in server
 - fibril can send asynchronous messages and wait for them later

Asynchronous framework (II)





Asynchronous framework (II)



- Waiting for a request
 - callid = async_get_call(&call)

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- ipc_answer_n(callid, retval, ...)

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- Send one message with n arguments
 - msgid = async_send_n(phone, method, ..., &answer)

- Waiting for a request
 - callid = async_get_call(&call)
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- ipc_answer_n(callid, retval, ...)

- Send one message with *n* arguments
 - msgid = async_send_n(phone, method, ..., &answer)
- Wait for an answer to a sent message
 async wait for(msgid, &retval0)

Using async framework (II)

- Send of *n* arguments and receive of *m* return values combined
 - retval0 = async_req_n_m(phone, method, ..., ...)

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- Send of *n* arguments and receive of *m* return values combined
 - retval0 = async_req_n_m(phone, method, ..., ...)
- Sharing memory
 - async_share_in/out_start(phone, ...)
 - async_share_in/out_receive(&callid, ...)
 - async_share_in/out_finalize(callid, ...)

Using async framework (III)

- Copying data
 - async_data_read/write_start(phone, ...)
 - async_data_read/write_receive(&callid, ...)
 - async_data_read/write_finalize(callid, ...)

Using async framework (III)

- Copying data
 - async_data_read/write_start(phone, ...)
 - async_data_read/write_receive(&callid, ...)
 - async_data_read/write_finalize(callid, ...)
- Fibrils often need to be synchronized
 - Fibril synchronization primitives
 - Mutexes
 - Readers-Write locks
 - Condition variables

Code example

```
req = async_send_2(vfs_phone, VFS_IN_MOUNT, dev_handle, flags, NULL);
rc = async_data_write_start(vfs_phone, (void *) mpa, mpa_size);
if (rc != EOK) {
```

```
}
rc = async_data_write_start(vfs_phone, (void *) opts, str_size(opts));
if (rc != EOK) {
```

```
}
rc = async_data_write_start(vfs_phone, (void *) fs_name, str_size(fs_name));
if (rc != EOK) {
```

```
}
/* Ask VFS whether it likes fs_name. */
rc = async_req_0_0(vfs_phone, IPC_M_PING);
if (rc != EOK) {
```

```
}
async_wait_for(req, &rc);
```

if (read)

res = async_data_read_receive(&callid, NULL); else

res = async_data_write_receive(&callid, NULL);
if (read)

fibril_rwlock_read_lock(&file->node->contents_rwlock); else

fibril_rwlock_write_lock(&file->node->contents_rwlock); msg = async_send_3(fs_phone, read ? VFS_OUT_READ : VFS_OUT_WRITE, file->node->dev_handle, file->node->index, file->pos, &answer); ipc_forward_fast(callid, fs_phone, 0, 0, 0, IPC_FF_ROUTE_FROM_ME); async_wait_for(msg, &rc); if (read)

fibril_rwlock_read_unlock(&file->node->contents_rwlock); else

fibril_rwlock_write_unlock(&file->node->contents_rwlock); ipc_answer_1(rid, rc, bytes);

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res = async_data_write_receive(&callid, NULL);
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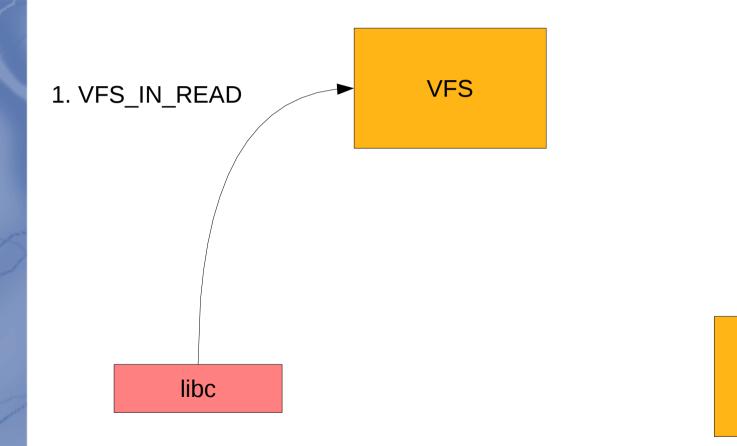
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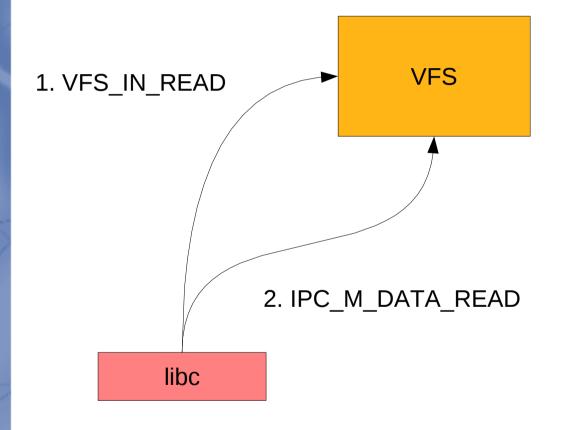


libc

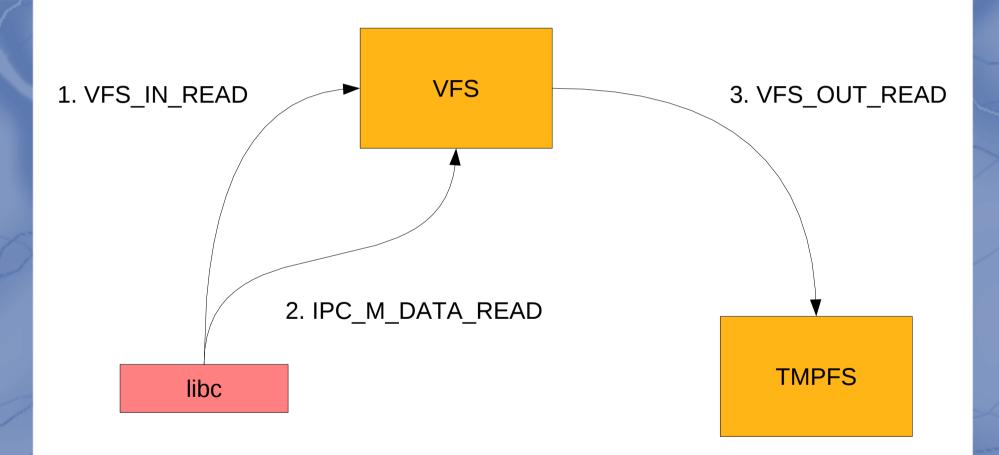
TMPFS

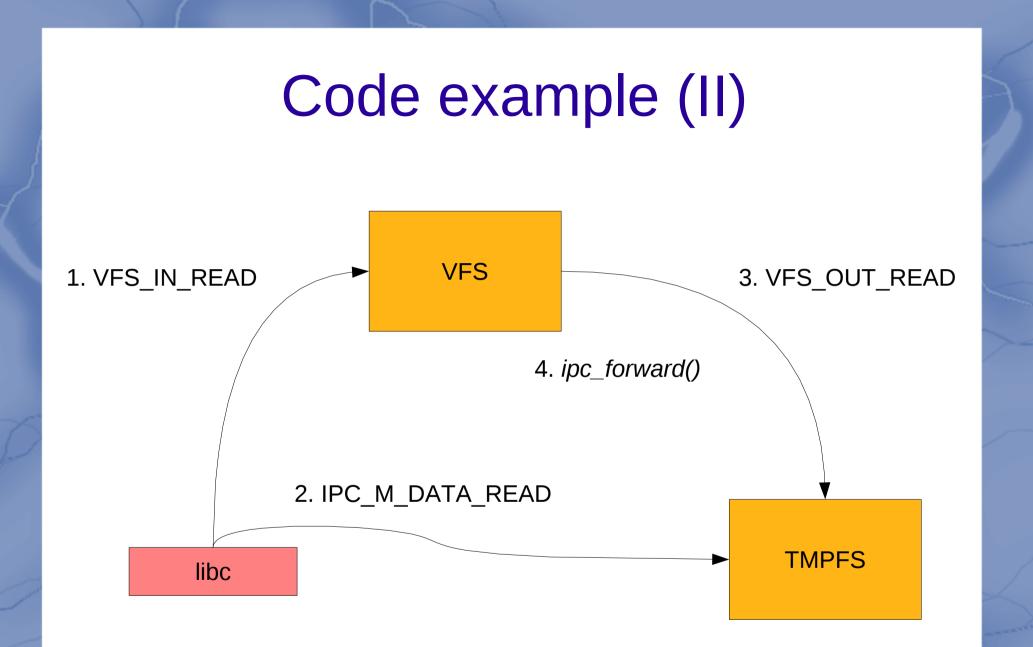
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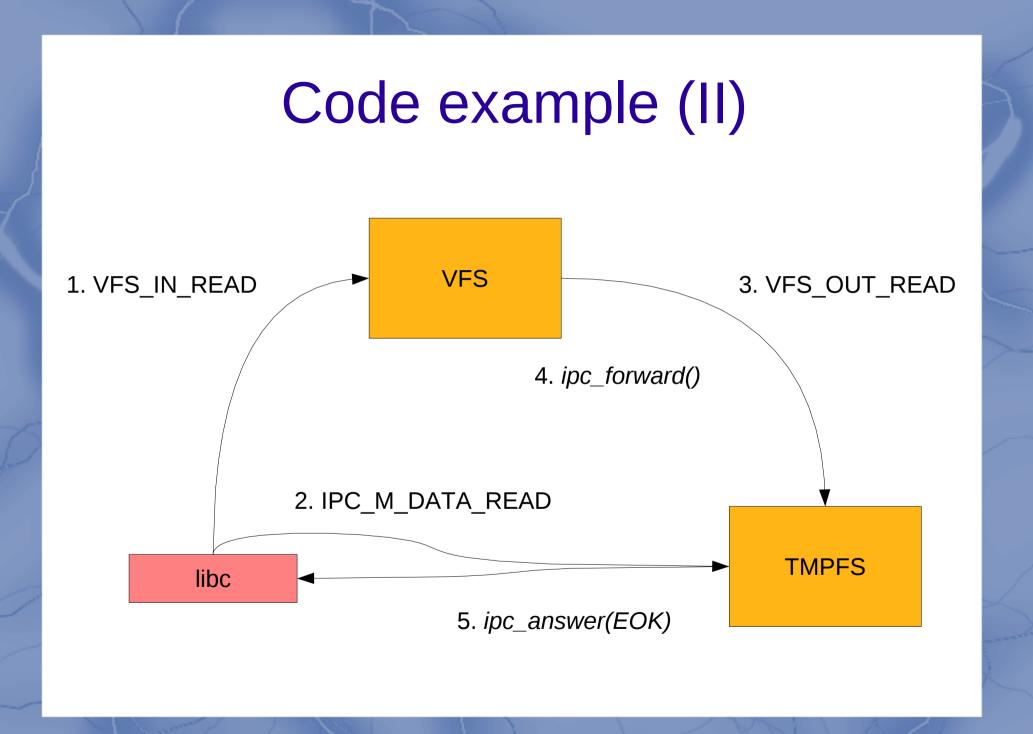


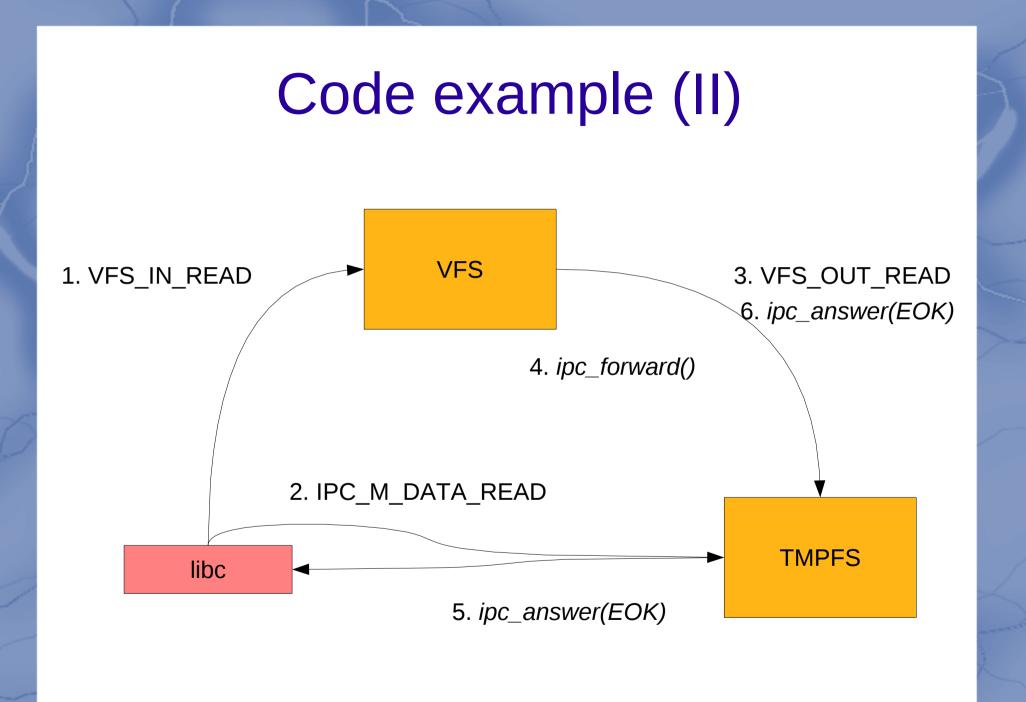


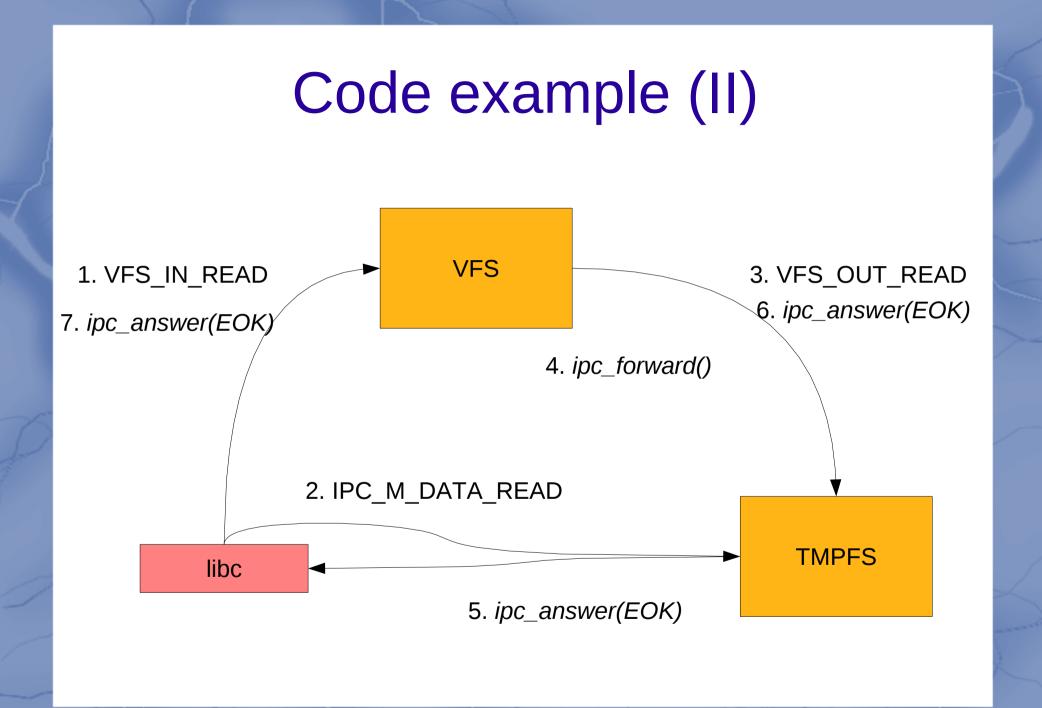
TMPFS











Demo

Questions?

www.helenos.org

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